

OPASKA!

- ☞ Ovi materijali namijenjeni su isključivo studenticama/studentima koji su upisali predmet "Računala i procesi" na FER-u u šk. g. 2002/2003.
- ☞ Za svako drugo korištenje potrebna je pismena suglasnost autora!
- ☞ Materijali služe kao pomoć u praćenju predavanja, a ne kao njihova zamjena te se ne mogu tumačiti izvan konteksta predavanja!

M. Žagar, 2002-10-01



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Mario Žagar



Sveučilište u Zagrebu

Fakultet elektrotehnike i računarstva
(FER)

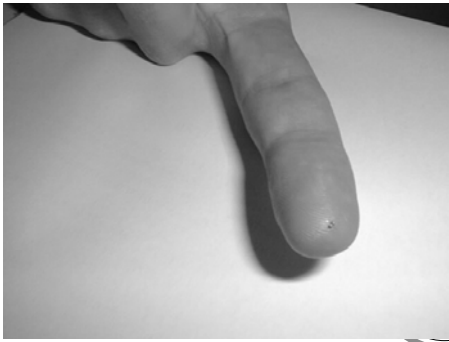
12. RIP - programiranje mikroracunala

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Predgovor I



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Predgovor II



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Predgovor III



RASIP, 1997.

RASIP, 1999.

Programsko inženjerstvo
može biti i nešto vrlo beznačajno

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Klasično programiranje (I)

- ☞ UNIX, syst. prog., ljuste, filtari,.....
- ☞ C, cc, ln, as, a.out, dbx, od,
- ☞ make, yacc, lex, time, prof, gprof,...
- ☞ sccs, nroff, bibl, vi, sort,.....
- ☞ HTML, WWW, cgi,.....
- ☞ Znanje koje se podrazumijeva !
- ☞ lit.:
 - M.Ž., UNIX i kako ga koristiti,
 - M.Ž., UNIX i kako ga iskoristiti



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Klasično programiranje (II)

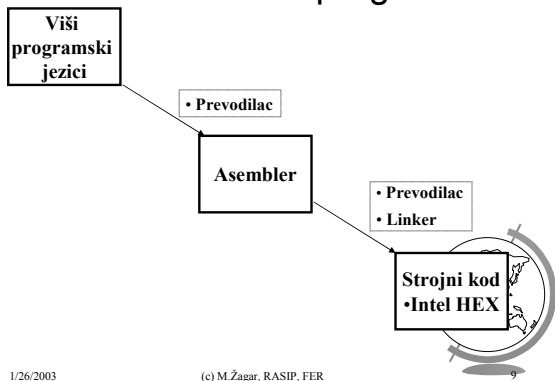
- ☞ WIN 3.11, Windows95, Windows98, NT, Windows 2000
- ☞ VisualBasic, C++, Java
- ☞ X11, Motif,
- ☞ Baze (SQL), G, ...



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Razine programa



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Viši programski jezici

- Formalni opisni jezik kojim programer opisuje što mikroprocesor treba napraviti.
- Notacija kojom se programer služi lakša je za snalaženje nego u assembleru.
- Svaka naredba u višem programskom jeziku odgovara nizu naredaba u strojnom jeziku.

U nastavku, primjeri programskog jezika C, C++



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Asembler

- Programski jezik koji omogućava programeru pisanje programa koristeći mnemonike,
- Mnemonici - razina strojnog koda,
- Assembler je simbolički programski jezik niske razine (eng. LOW-LEVEL LANGUAGE),
- Omogućava korištenje mnemonika, makro naredaba, labela, ključnih riječi (npr.: ORG, DW, DB ...),
- Omogućava jednostavan pristup svim registrima mikroročunala.

U nastavku primjeri za Z80, i8051 i PIC16c54



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Strojni kod

- Osnovni programski jezik koje mikroprocesor može izvršavati bez prevođenja.
- Sastoji se od niza brojeva koji predstavljaju naredbe mikroprocesora
- Za zapis strojnog koda često se koristi INTEL HEX FORMAT (ASCII)



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FORMAT INTEL HEX

format zapisa:

start znak →: **NN aaaa 00 xxxxxxxx...xxxx ss**

↙ ↘
↙ ↘
↙ ↘

broj znakova kontrolni znak kontrolni zbroj
 adresa niza podaci

- *start znak* - početak svakog retka
- *broj znakova* - broj znakova koje se upisuju na adresu *aaaa*
- *adresa niza* - logička adresa niza u memoriji počevši od *aaaa*
- *kontrolni zbroj* - broj koji dodan ukupnom 8-bitnom zbroju niza daje zbroj nula

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FORMAT INTEL HEX

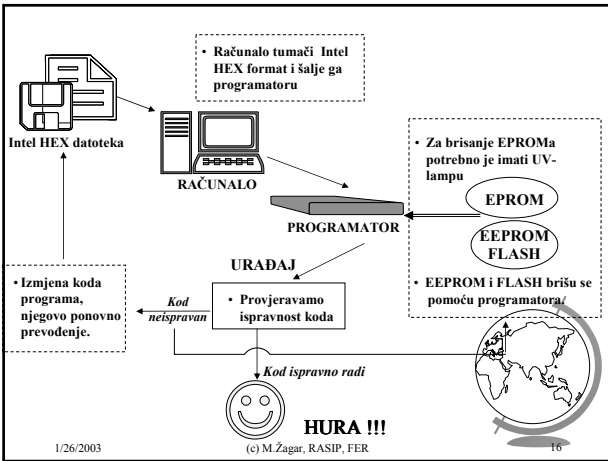
```

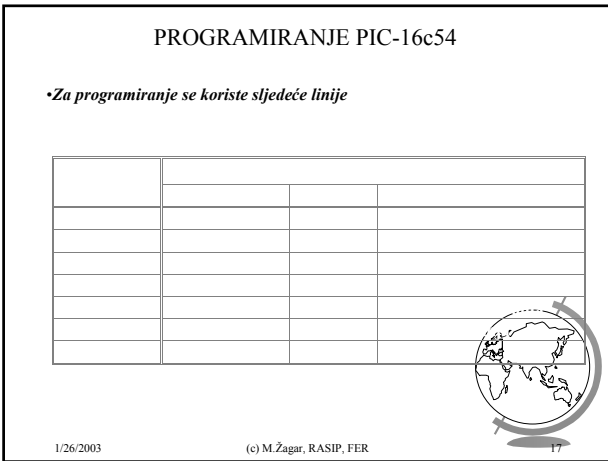
:20 01 00 00 F3 ...      00
:20 01 20 00 30 ...      01
:20 01 40 00 21 ...      00
:20 01 60 00 D6 ...      +01
:01 01 80 00 87 F7       ----
:00 01 00 01 FE          02
:BBAAAACCCDDDDD...DDDDSS  FD
                                FE
    
```

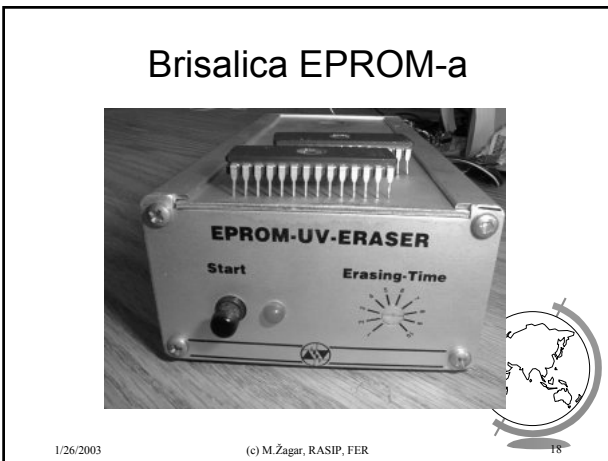
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Z80	I8051	PIC16c54	
	<code>c = 10; /* a je tipa int*/</code>		
<code>LD HL,0</code>	<code>MOV R7,0x0A</code>	<code>MOVLW 0Ah</code>	
<code>ADD HL,SP</code>		<code>MOVWF ?(a_main+4)</code>	
<code>EX DE,HL;</code>			
<code>LD HL,10</code>			
<code>LD A,L</code>			
<code>LD (DE),A</code>			
	<code>a++ ;</code>		
<code>LD HL,3</code>	<code>INC R5</code>	<code>INCF ?(a_main+0)</code>	
<code>ADD HL,SP</code>	<code>CJNE R5,#0x00,L20</code>	<code>BTFSCL status_2</code>	
<code>LD D,H</code>	<code>INC R4</code>	<code>INCF ?(a_main+0+1)</code>	
<code>LD E,L</code>	<code>L20: NOP</code>		
<code>CALL CCGINT##</code>			
<code>INC HL</code>			
<code>CALL CCPINT##</code>			
<code>DEC HL</code>			

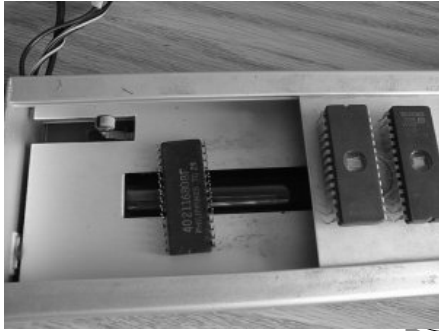
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Brisalica EPROM-a iznutra



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Programator EPROM-a (HI-LO)



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Programator EPROM-a (domaći)



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PROGRAMIRANJE PIC-16c54

•Postupak programiranja:

- Podižemo napon na pinu /MCLR od 0V do 13V i držimo pin T0CKI na 5V.
- Programski brojač se postavlja u "0xFFFF", zato što je na početku /MCLR na 5V što predstavlja reset procesora.
- Pulsiranjem OSC1 pina povećavamo programsko brojilo
- Spuštanjem pina T0CKI na 0V pohranjujemo podatak na pinovima D0 - D11 u EPROM
- Nakon što programsko brojilo dođe do zadnje lokacije "0xFFFF", njegovo daljnje povećavanje znači adresiranje funkcijskog dijela EPROMA



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PIC16C54 - u kutiji šibica



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Mikrokontroleri na sve strane (I)



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Mikrokontroleri na sve strane (II)



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Mikrokontroleri na sve strane (III)



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Mikrokontroleri na sve strane (IV)



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PIC16C7X (I)

PIC16C7X - 8-Bit CMOS Microcontrollers with A/D Converter

PIC16C7X Microcontroller Core Features:

- High-performance RISC CPU
- Only 35 single word instructions to learn
- All single cycle instructions except for program branches which are two cycle
- Operating speed: DC - 20 MHz clock input
- DC - 200 ns instruction cycle
- Up to 8K x 14 words of Program Memory, up to 368 x 8 bytes of Data Memory (RAM)
- Interrupt capability
- Eight level deep hardware stack
- Direct, indirect, and relative addressing modes
- Power-on Reset (POR)
- Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Watchdog Timer (WDT) with its own on-chip RC oscillator for reliable operation



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PIC16C7X (II)

- Programmable code-protection
- Power saving SLEEP mode
- Selectable oscillator options
- Low-power, high-speed CMOS EPROM technology
- Fully static design
- PIC16C72, PIC16C73, PIC16C73A, PIC16C74, PIC16C74A, PIC16C76, PIC16C77
- Wide operating voltage range: 2.5V to 6.0V
- High Sink/Source Current 25/25 mA
- Commercial, Industrial and Extended temperature ranges
- Low-power consumption:
 - < 2 mA @ 5V, 4 MHz
 - 15 mA typical @ 3V, 32 kHz
 - < 1 mA typical standby current



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PIC16C7X (III)

PIC16C7X Peripheral Features:

- Timer0: 8-bit timer/counter with 8-bit prescaler
- Timer1: 16-bit timer/counter with prescaler, can be incremented during sleep via external crystal/clock
- Timer2: 8-bit timer/counter with 8-bit period register, prescaler and postscaler
- Capture, Compare, PWM module(s)
 - Capture is 16-bit, max. resolution is 12.5 ns,
 - Compare is 16-bit, max. resolution is 200 ns,
 - PWM max. resolution is 10-bit
- 8-bit multichannel analog-to-digital converter
- Synchronous Serial Port (SSP)
- Universal Synchronous Asynchronous Receiver Transmitter (USART)
- Parallel Slave Port (PSP) 8-bits wide, with ext. RD, WR and CS controls
- Brown-out detection circuitry for Brown-out Reset (BOR)

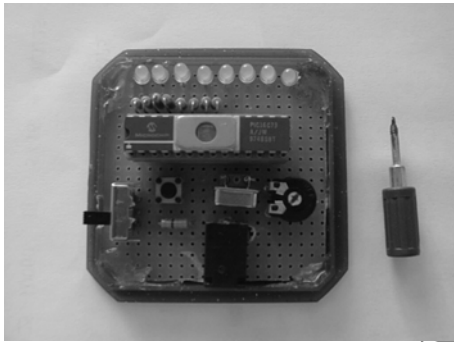


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PIC16C73 - u kutiji od nakita

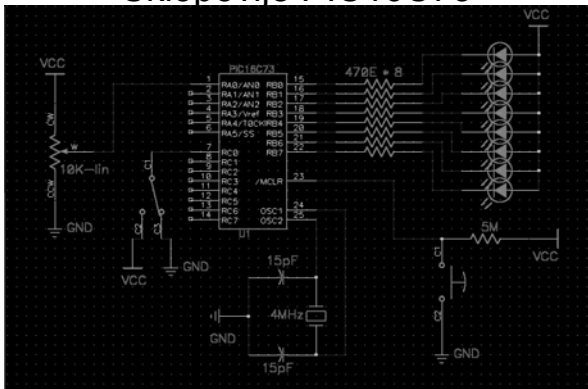


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Sklopovlje PIC16C73



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Asembler (I)

```

LIST    p=16c73 ; PIC16c73 is the target processor
#include "P16c73.INC" ; Include header file
TEMP1  EQU    0x3A
TEMP2  EQU    0x3B
TEMP3  EQU    0x3D

        GOTO   MAIN

WAIT:   MOVWF  TEMP1
        MOVLW 0xFF
        MOVWF  TEMP2
        MOVWF  TEMP3

WAIT1:  DECFSZ TEMP2
        GOTO  WAIT1
        DECFSZ TEMP3
        GOTO  WAIT1
        DECFSZ 0x3A
        GOTO  WAIT1
        RETURN
    
```

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Assembler (II)

```

RUNLED:
MOV LW 0
MOV F TRISB


LOOP:
INCF PORTB
MOV LW 1
CALL WAIT
GOTO LOOP

AD2LED:
MOV LW 0
MOV F TRISB
MOV LW 0x0C1
MOV F ADCON0
CLRF ADCON1
MOV LW 0xFF
MOV F PORTB
MOV LW 20
CALL WAIT
MOV LW 0x00
MOV F PORTB
BSF ADCON1,2

LOOP1:
BTFSF ADCON1,2
GOTO LOOP1
MOV F ADRES
MOVWF PORTB
BSF ADCON1,2
GOTO LOOP1

MAIN:
BTFSF PORTB,0
GOTO AD2LED
GOTO RUNLED

END
    
```




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C

```

#include "pic1673.h"
/* Mala Pauza */
void wait(int a){
    int i,j;
    for (j=0;j<a;j++){
        for (i=0;i<2000;i++){
            i=i;
        }
    }
}
/* Trcece diode*/
void RunLED(){
    TRISB=0;
    while(1){
        PORTB=PORTB+1;
        wait(1);
    }
}

/* AD pretvorba */
void AD2LED(){
    TRISB=0; // init AD
    ADCON0=0xC1;
    ADCON1=0x00;
    PORTB=0xFF;
    wait(20);
    PORTB=0x00;
    ADGO=1;
    while(1){
        if (ADGO==0){
            PORTB=ADRES;
            ADGO=1;
        }
    }
}
/* Glavni Program */
void main(){
    if (RC0==0) {
        RunLED();
    }else {
        AD2LED();
    }
}
    
```




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Veza C--, Z80-ASM

☞ CCZ--

☞ telnet ccz--



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